

# **Type 8692/8693/8792/8793**

CANopen

Objects

Document version 1.05

Supplement to Operating Instructions

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# 1 History

Document version	Date	Changes
1.05	2021-03-01	Fix object index of PVanalog
1.04	2019-11-20	Added LED Extern Color object 0x2122
1.03	2019-07-08	Added Locating function object 0x2101 Added Maintenance Function object 0x210A Added Code protection object 2C01sub7 and and 2C01sub8
1.02	2018-07-26	Added NamurStatus object 0x2506 PVmin, PVmax, SPmin, SPmax moved to other Index
1.01	2018-02-01	Initial released version

## 2 Overview

Used datatypes:

UINT8	8 bit: unsigned integer
UINT16	16 bit: unsigned integer
UINT32	32 bit: unsigned integer
REAL32	32 bit: float value IEEE 754
String	C-string

## 3 Objects

Column “access type” describes the general CAN open access rights.

Column “Config-Client” marks the objects that are handled and transferred between the devices using the Config-Client.

### 3.1 0x2000 Buerkert Device Description Object

sub	name	description	access type	Config-Client
1	Device Name	Unique device name Used to identify the device in a bueS system by name (e.g. Buerkert Communicator) (linked to User Configuration Object)	RO	
2	Ident Number	Device ID No. (linked to Common Object)	RO	
3	Manufacture Date	(linked to Common Object)	RO	
4	Software Ident Number	ID No. of firmware	RO	
5	Software Version	Version No. of firmware	RO	
6	Hardware Version	Version No. of hardware	RO	
7	Serial Number	Serial No. device (linked to Common Object)	RO	
8	Product Code	Manufacturers product code (type number) (linked to Common Object)	RO	
9	Product Group	Buerkert specific product group like sensor, actuator, ... Used for bueS system configuration	RO	

### 3.2 0x2001

### Device Communication Object

sub	name	description	access type	Config- Client
1	Baudrate	<i>Specified by CANopen (details see attachment Baud rates)</i>	RW	x
2	Address	<i>Device address range 0..127 handled automatically in bueS mode</i>	RW	x
4	Reset	<i>Handles different device resets 1: Communication Reset 2: Node reset (device reset) 3: bueS reset 4: Factory reset 5: restart device in boot loader mode</i>	RW	
5	bueS Version	version number of the bueS driver	RO	
6	Rx error count	occurred Rx errors since devices lifetime	RO	
7	Rx error count max	maximal value of occurred Rx errors	RW	
8	Tx error count	occurred Tx errors since devices lifetime	RO	
9	Tx error count max	maximal value of occurred Tx errors	RW	
A	CAN operation status	operation status of CAN	RO	
C	Deallocation delay	delay[ms] that partner allocation waits after remove node before start search again	RW	x
D	EDS Version	Version of the EDS file		

### 3.3 0x2002

### User Configuration Object

sub	name	description	access type	Config- Client
1	Unique Device Name	<i>Taken over to Buerkert Device Description Object during device start.</i>	RW	x
2	Location Information	<i>Additional user information about the devices location</i>	RW	x
3	User Description	<i>Additional user information about the device</i>	RW	x
4	Displayed Device Name	<i>Device name which is displayed</i>	RW	x

## 3.4 0x2004 Device Status Object

sub	name	description	access type	Config-Client
1	Device Status NamurNe107	Corresponds to the device status. <sup>1)</sup>	RO	
2	Device Temperature	Devices temperature in kelvin	RO	
3	Device Supply Voltage	Supply voltage in volt	RWR	
4	Operation Time_[s]	Devices operating time counter as seconds	RO	
5	Maximum Device Temperature	Maximum internal devices temperature in kelvin during devices lifetime	RO	
6	Minimum Device Temperature	Minimum internal devices temperature in kelvin during devices lifetime	RO	
7	Maximum Device Supply Voltage	Max value of devices power supply in volts since start-up	RO	
8	Minimum Device Supply Voltage	Max value of devices power supply in volts since start-up	RO	
E	Trans Mem Status	Represents the status of the transferable memory (SIM card). 0:Unknown 1:MemoryAvailable 2:MemoryNotAvailable 3:MessageAcknowledged 4:MemoryOptional	RO	

1)

Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0
Gateway: 0 - run 1 - stop  0 if no gateway is supported by device.	F(x): 0 - run 1 - stop  0 if no F(x) functionality is supported by device.	Namur mode: 0 - auto 1 - manual 2 - flashing		Namur state: 0 - normal 1 - diagnose active 2 - maintenance required 3 - out of specification 4 - warning 5 - error			

## 3.5 0x2100 Get Mapping Function

Internal function



### 3.6 0x2101 Locating Function

Function for locating a device. Device LED flashes for several times by setting call/cancel to 1.

sub	name	description	access type	Config- Client
1	call/cancel	bueS internal function	RW	

### 3.7 0x2102 Blockdownload Config Function

Internal function

### 3.8 0x2103 Persistent Storage Function

Internal function

### 3.9 0x210A Trigger Maintenance Function

Put device into maintenance state. The blue Namur LED identifies the relevant device for maintenance by setting call/cancel to 1.

sub	name	description	access type	Config- Client
1	call/cancel	bueS internal function	RW	

### 3.100x2120 LED Modi

sub	name	description	access type	data type	data memory	factory reset	device reset
0x0	LED Modi	<p>Select LED indicator</p> <p>Please refer to the operating instructions for a description of the possible indicator modes.</p> <p>0 – NAMUR mode</p> <p>1 – Valve mode* (position signal, no errors) *</p> <p>2 – Valve mode* + errors (red) *</p> <p>3 – Valve mode* + errors (red) + warnings (orange, yellow, blue) *</p> <p>4 – Fixed color mode configured by object 0x2122 (LED Extern Color))</p> <p>6 – (Top) LEDs off</p> <p>*Colors for valve mode are defined in object index 0x2121 Valve Mode Configuration</p>	RW	UI32	x	x	

### 3.11 0x2122 LED Extern Color

sub	name	description	access type	data type	data memory	factory reset	device reset																				
0x0	LED Extern Color	<p>Setting object 0x2120 LED Modi to 4 (Fixed Color) the color of TOP LEDs is controlled externally by writing a corresponding value to this object:</p> <table><tr><th>Value</th><th>TOP LED Color</th></tr><tr><td>0x10000001</td><td>White</td></tr><tr><td>0x10000006</td><td>Red</td></tr><tr><td>0x10000005</td><td>Orange</td></tr><tr><td>0x10000004</td><td>Yellow</td></tr><tr><td>0x10000002</td><td>Green</td></tr><tr><td>0x10000003</td><td>Blue</td></tr><tr><td>0x00FFFF00</td><td>Teal</td></tr><tr><td>0x00FF00FF</td><td>Pink</td></tr><tr><td>0x10000000</td><td>LEDs Off</td></tr></table>	Value	TOP LED Color	0x10000001	White	0x10000006	Red	0x10000005	Orange	0x10000004	Yellow	0x10000002	Green	0x10000003	Blue	0x00FFFF00	Teal	0x00FF00FF	Pink	0x10000000	LEDs Off	RW	UI32	x	x	
Value	TOP LED Color																										
0x10000001	White																										
0x10000006	Red																										
0x10000005	Orange																										
0x10000004	Yellow																										
0x10000002	Green																										
0x10000003	Blue																										
0x00FFFF00	Teal																										
0x00FF00FF	Pink																										
0x10000000	LEDs Off																										

### 3.120x2200 Buerkert Driver Archive

Internal object

### 3.13 0x2220 EDS

Internal object

### **3.14 0x2400**

### **Sensor Type**

Internal object

### **3.15 0x2420**

### **No Measure Values**

Internal object

### **3.16 0x2421**

### **No Control Values**

Internal object

### **3.17 0x2422**

### **No Calibration Values**

Internal object

## 3.180x2500 POS

sub	name	description	access type	Config-Client
1	Value	current position of valve in %	RWR	
2	Unit	0xFE000000 %	RO	
3	Name	POS objects name	RO	
4	Classification	0x000E bueS specific	RO	
5	Datatype	0x08 REAL32	RO	
6	Precision	bueS specific	RO	
7	Feature Group	0 bueS specific Used for automatic configuration in bueS systems	RW	x

## 3.190x2501 CMD

sub	name	description	access type	Config-Client
1	Value	Current position setpoint of the valve in %, which is used by position controller. This is the set point after the signal processing functions (CHARACT, DIR.CMD, SPLTRNG) are applied	RWR	
2	Unit	0xFE000000 %	RO	
3	Name	CMD* objects name	RO	
4	Classification	0x000E bueS specific	RO	
5	Datatype	0x08 REAL32	RO	
6	Precision	bueS specific	RO	
7	Feature Group	0 bueS specific Used for automatic configuration in bueS systems	RW	x

## 3.20 0x2502 CMDanalog

sub	name	description	access type	Config-Client
1	Value	Current position setpoint for the position controller from analog input in %.	RWR	
2	Unit	0xFE000000 %	RO	
3	Name	CMD analog objects name	RO	
4	Classification	0x000E bueS specific	RO	
5	Datatype	0x08 REAL32	RO	
6	Precision	bueS specific	RO	
7	Feature Group	0 bueS specific Used for automatic configuration in bueS systems	RW	x

## 3.21 0x2503 SPanalog

Only available for devices with process controller function

sub	name	description	access type	Config-Client
1	Value	Current process setpoint from analog input for the process controller.	RWR	
2	Unit	0xFE000000 bueS specific SI unit : NI/min Other units are handled by display or Buerkert Communicator	RO	
3	Name	SP* objects name	RO	
4	Classification	0x000E bueS specific	RO	
5	Datatype	0x08 REAL32	RO	
6	Precision	bueS specific	RO	
7	Feature Group	0 bueS specific Used for automatic configuration in bueS systems	RW	x

## 3.22 0x2504 PVanalog

Only available for devices with process controller function

sub	name	description	access type	Config-Client
1	Value	Current measured process value from analog input for the process controller.	RWR	
2	Unit	0xFE000000 bueS specific SI unit : NI/min Other units are handled by display or Buerkert Communicator	RO	
3	Name	PV* objects name	RO	
4	Classification	0x000E bueS specific	RO	
5	Datatype	0x08 REAL32	RO	
6	Precision	bueS specific	RO	
7	Feature Group	0 bueS specific Used for automatic configuration in bueS systems	RW	x

## 3.23 0x2540 CMDdigital

sub	name	description	access type	Config-Client
1	Value	Position controller set point in %	RWW	
2	Unit	0xFE000000 %	RO	
3	Name	CMD objects name	RO	
4	Classification	0x0003 bueS specific	RO	
5	Datatype	0x08 REAL32	RO	
6	Precision	bueS specific	RO	
7	Feature Group	0 bueS specific Used for automatic configuration in bueS systems	RW	x

## 3.24 0x2541 SPdigital

Only available for devices with process controller function

sub	name	description	access type	Config-Client
1	Value	Process controller set point	RWW	
2	Unit	0xFE000000 bueS specific SI unit : Nl/min Other units are handled by display or Buerkert Communicator	RO	
3	Name	SP objects name	RO	
4	Classification	0x0003 bueS specific	RO	
5	Datatype	0x08 REAL32	RO	
6	Precision	bueS specific	RO	
7	Feature Group	0 bueS specific Used for automatic configuration in bueS systems	RW	x

## 3.25 0x2542 PVdigital

Only available for devices with process controller function

sub	name	description	access type	Config-Client
1	Value	Current process value. Only applicable if PV-Input is BUS	RWW	
2	Unit	0xFE000000 bueS specific SI unit : Nl/min Other units are handled by display or Buerkert Communicator	RO	
3	Name	PV objects name	RO	
4	Classification	0x0003 bueS specific	RO	
5	Datatype	0x08 REAL32	RO	
6	Precision	bueS specific	RO	
7	Feature Group	0 bueS specific Used for automatic configuration in bueS systems	RW	x

## 3.26 0x2542 MTEMPdigital

Only available for devices with FMR function

sub	name	description	access type	Config-Client
1	Value	Current temperature of fluid	RWW	
2	Unit	0xFE000000 bueS specific SI unit : Nl/min Other units are handled by display or Buerkert Communicator	RO	
3	Name	MTEMPdigital objects name	RO	
4	Classification	0x0003 bueS specific	RO	
5	Datatype	0x08 REAL32	RO	
6	Precision	bueS specific	RO	
7	Feature Group	0 bueS specific Used for automatic configuration in bueS systems	RW	x

## 3.27 0x2C00 XControl

sub	name	description	access type	Config-Client
0x0F	TIMEopen	Time to open valve measured by last X.Tune	RO	
0x10	TIMEclose	Time to close valve measured by last X.Tune	RO	
0x14	TUNEflags	0 if last tune was successful	RW	
0x16	YBfric	Friction compensation parameter YB	RW	
0x17	YEfric	Friction compensation parameter YE	RW	



## 3.28 0x2C01

## Display

sub	name	description	access type	Config- Client
0x05	Menu_Items	Bitfield to Activate/Deactivate functions from ADD.FUNCTION menu Bit0 – Bit6: unused Bit7: CHARACT Bit8: CUTOFF Bit9: DIR.CMD Bit10: DIR.ACT Bit11: SPLTRNG Bit12: X.LIMIT Bit13: X.TIME Bit14: X.CONTROL Bit15: P.CONTROL (only 8693/8793) Bit16: SECURITY Bit17: SAFEPOS Bit18: SIG.ERROR Bit19: BINARY.IN Bit20: OUTPUT Bit21: CAL.USER Bit22: SET.FACTORY Bit23: SERVICE.BUES Bit24: EXTRAS Bit25: POS.SENSOR (only type 879X) Bit26: SERVICE Bit27: SIMULATION Bit28: DIAGNOSE Bit29: F.CONTROL (only with FMR option)	RW	X
0x07	mCODEfunc	Bitfield to lock menus (SECURITY function) Bit0: MAIN Bit1: MANU/AUTO Bit2: ADDFUNC Bit3: X.TUNE Bit4: P.Q'LIN Bit5: P.TUNE	RW	X
0x08	mCODE	Code of SECURITY function 0-9999	RW	X
0x0C	SP_Manual	SP which is used when mPCONsetp (0x2C02sub9) is 0 (intern). Unit is bueS specific SI unit	RW	X

## 3.29 0x2C02 PCONTROL

Only available for devices with process controller function

sub	name	Description	access type	Config-Client
2	FTfgPV	Predefined filter setting Values for the process value input 0: Filter 0 (10 Hz) 1: Filter 1 (5 Hz) 2: Filter 2 (2 Hz) 3: Filter 3 (1 Hz) 4: Filter 4 (0,5 Hz) 5: Filter 5 (0,2 Hz) 6: Filter 6 (0,1 Hz) 7: Filter 7 (0,07 Hz) 8: Filter 8 (0,05 Hz) 9: Filter 9 (0,03 Hz)	RW	X
3	DBDp	Deadband of process controller in % (Scaled with PCOmin and PCOmax)	RW	X
4	KP	Proportional gain of the process controller	RW	X
5	TN	Integral action time of the process controller in s	RW	X
6	TV	Derivative action time of the process controller in s	RW	X
7	X_0	Operating point of the process controller, position in %	RW	X
8	mPCONsetp	0:SP source is SP_Manual (2C01subC) 1: SP source is extern (fielbus or analog input)	RW	X
9	mPCONinp	Selecting the type of analog input for ProcessValue of the process controller 0:FMR (only if FMR device) 1:4-20 mA 2:Frequency 3:PT100 4:BUS (BueS/Fieldbus)	RW	X
0xA	mPcolnitMode	P.CO initialization mode 0: Standard 1: Bumpless 2: Zero-Init	RW	X
0xF	PT100offset_user	PT100 calibration offset	RW	X

<b>0x10</b>	SCALunit	<i>Unit of process controller</i> 0: l/s <sup>1</sup> 1: l/min <sup>1</sup> 2: l/h <sup>1</sup> 3: m <sup>3</sup> /min <sup>1</sup> 4: m <sup>3</sup> /h <sup>1</sup> 5: UG/s <sup>1</sup> 6: UG/min <sup>1</sup> 7: UG/h <sup>1</sup> 8: IG/s <sup>1</sup> 9: IG/min <sup>1</sup> 10: IG/h <sup>1</sup> 11: °C <sup>2</sup> 12: °F <sup>2</sup> 13: m/s 14: bar 15: mbar 16: psi 17: % 18: mm 19: m 20: Liter 21 : Nl/s 22 : Nl/min 23 : Nl/h 24: none	RW	X
<b>0x12</b>	SCALkfact	<i>PV-scaling if frequency input is used</i>	RW	X
<b>0x15</b>	SCALdp	<i>Decimal point of process controller scaling (0-3)</i>	RW	X
<b>0x16</b>	SCALdp_kfact	<i>Decimal point of process controller scaling when frequency input is used</i>	RW	X
<b>0x17</b>	PCONact	<i>Deactivate process controller via bueS/fieldbus</i> 0: process controller inactive 1: process controller active	RW	
<b>0x18</b>	PVmin	<i>Lower scaling point PV (bueS specific SI unit)</i>	RW	X
<b>0x19</b>	PVmax	<i>Upper scaling point PV (bueS specific SI unit)</i>	RW	X
<b>0x1A</b>	SPmin	<i>Lower scaling point SP (bueS specific SI unit)</i>	RW	X
<b>0x1B</b>	SPmax	<i>Upper scaling point SP (bueS specific SI unit)</i>	RW	X

<sup>1</sup> mPCONinp = 2 (Frequency) can only use values 0 - 10

<sup>2</sup> mPCONinp = 3 (PT100) can only use values 11 and 12

## 3.30 0x2C04 CHARACT

sub	name	description	access type	Config- Client
1	mCHARACT	<i>Charact curve selected</i> 0: No charact curve 1:Charact Curve 1:25 2:Charact Curve 1:33 3:Charact Curve 1:50 4:Charact Curve 25:1 5:Charact Curve 33:1 6:Charact Curve 50:1 7:FREE (See0x2C11 for definig the values) See User Manual for description of the function.	RW	X

## 3.31 0x2C08 DIRCMD

sub	name	description	access type	Config- Client
1	mDIRcmd	0: Rise (0V > 0%) 1: Fall (0V -> 100%) See User Manual for description of the function.	RW	X

### 3.32 0x2C09 DIRACT

sub	name	description	access type	Config- Client
1	mDIRact	0: Rise (lower position > 0%) 1: Fall (upper position-> 100%) See User Manual for description of the function.	RW	X

### 3.33 0x2C0A CUTOFF

sub	name	description	access type	Config- Client
1	CUTOFFmin	Lower CUTOFF level in %	RW	X
2	CUTOFFmax	Upper CUTOFF level in %	RW	X
3	mCUTOFFtype	0: CUTOFF function is based on SP 1: CUTOFF function is based on CMD See User Manual for description of the function.	RW	X

### 3.34 0x2C0B XLIMIT

sub	name	description	access type	Config- Client
1	POSmin	Lower position for X.LIMIT in %	RW	X
2	POSmax	Upper position for X.LIMIT in %	RW	X

### 3.35 0x2C0C XControl\_User

sub	name	description	access type	Config- Client
0x01	DBDx	Deadband of the position controller in %	RW	X
0x02	KPclose	Proportional gain for opening the valve	RW	X
0x03	KPopen	Proportional gain for closing the valve	RW	X

### 3.36 0x2C0D XTIME

sub	name	description	access type	Config- Client
1	XTIMEopen	Limited opening time of the valve in s	RW	X
2	XTIMEclose	Limited closing time of the valve in s	RW	X

### 3.37 0x2C0E BININ

sub	name	description	access type	Config- Client
1	mBINfunc	Binary input function 0: Safepos 1: Hand/Auto 2: start X.Tune 3: X.CO/P.CO 4: LeakChar (FMR)	RW	X
2	mBINtype	0: Active high 1: Active low	RW	X

### 3.38 0x2C10 SAFEPOS

sub	name	description	access type	Config- Client
1	mSAFEpos	Position used as safepos in %	RW	X

### 3.39 0x2C11 CHARACTy

sub	name	description	access type	Config- Client
0x01... 0x15	sub01 ... sub15	user-defined charact in 5% steps (0%, 5%, ..., 100%) It is used when object 0x2C04sub01 is set to "FREE"	RW	X

### 3.40 0x2C12 CHARACT\_kvuser

Only for FMR-devices

sub	name	description	access type	Config- Client
0x01... 0x15	sub01 ... sub15	user-defined kv charact in 5% steps (0%, 5%, ..., 100%)	RW	X

### 3.41 0x2C14 CHARleakp

Only for FMR-devices

sub	name	description	access type	Config- Client
0x01... 0x15	sub01 ... sub15	CHARleakp 5% steps (0%, 5%, ..., 100%)	RW	X

## 3.42 0x2C15 CHARleakq

Only for FMR-devices

sub	name	description	access type	Config- Client
0x01	RemoteType	0: dDIGITAL 1: dANALOG	RW	X
0x02	mTANcorr_activ	1: TAN-Correction is active 0: TAN-Correction is inactive	RW	X
0x03	AlphaPosSens	Used angle for TAN-Correction (+/- °)	RW	X

## 3.43 0x2C16 WMS

sub	name	description	access type	Config- Client
0x01	zOPmode	Get the current operating mode 0: Auto 1: Hand 2: X.Tune 9: P.Q.Lin 10 : P.Tune	RO	
0x0C	startTune	Start Tune via fieldbus 2: X.Tune 9: P.Q.Lin 10 : P.Tune  startTune is set back from device 0: TUNE successfully started 255: TUNE could not be started  Tune has finished when zOPmode changed back to Auto or Manual mode. Get result of last tune by reading object TUNEflags (2C00sub14))	RW	



## 3.44 0x2C17 Simulation

sub	name	description	access type	Config- Client
0x01	SIM_Ks	Proportional gain of simulated process	RW	X
0x02	SIM_Ts	Time constant in s of simulated process	RW	X
0x03	SIM_amp	Amplitude in % of simulated CMD	RW	X
0x04	SIM_per	Period in s of simulated CMD	RW	X
0x05	SIM_off	Offset in % of simulated CMD	RW	X
0x06	xSIMactiv	1: Activate actuator simulation 0: Deactivate actuator simulation	RW	
0x07	pSIMactiv	1: Activate process simulation 0: Deactivate process simulation	RW	
0x08	SP_MODactiv	Activate CMD simulation 0: extern (simulation off) 1: Sinus 2: Square 3: Triangle 4: mixed	RW	

## 3.45 0x2C18 Modeswitch

sub	name	description	access type	Config- Client
0x01	zOPmode	Get the current operating mode 0: Auto 1: Hand 2: X.Tune 9: P.Q.Lin 10 : P.Tune	RO	
0x0C	startTune	Start Tune via fieldbus 2: X.Tune 9: P.Q.Lin 10 : P.Tune  startTune is set back from device 0:TUNE successfully started 255:TUNE could not be started  Tune has finished when zOPmode changed back to Auto or Manual mode. Get result of last tune by reading object TUNEflags (2C00sub14))	RW	

### 3.46 0x2C23 SensorBreak

sub	name	description	access type	Config- Client
0x02	mERRpinp_func	0: signal break detection of PV inactive 1: signal break detection of PV active	RW	X
0x04	mSPoSpinp_func	0: no safepos when PV signal break detected 1: safepos when PV signal break detected	RW	X

### 3.47 0x2C39 F.Control

Only for FMR-devices

sub	name	description	access type	Config- Client
0x01	FMRtemp	Temperature of medium	RW	X
0x02	FMRdens	Density of medium	RW	X
0x03	FMRdiam	Diameter of valve	RW	X
0x04	FMRkvselect	Selection of kv charact 0: factory charact 1: user charact	RW	X
0x05	FMRsens	Source of medium temperature 0: Manual (2C29sub1) 1: analog input 2: BueS/fieldbus (2542sub1)	RW	X
0x06	mPCONleak	0: Leakage inactive 1: Leakage active	RW	X

### 3.48 0x2C42 SP\_UserUnit

sub	name	description	access type	Config- Client
	SP_UserUnit	SP in user unit which is shown on display	RWW	

3.490x2C42      PV\_UserUnit

sub	name	description	access type	Config- Client
	PV_UserUnit	PV in user unit which is shown on display	RWW	

## Attachment

### 3.50 Baud rates

The used baud rate can be set in Baudrate in the Device Communication Object (0x2001sub1). Supported baud rates are specified in the EDS-file.

Possible values are:

- 0: 1000 kbit/s
- 1: 800 kbit/s (not supported)
- 2: 500 kbit/s (default)
- 3: 250 kbit/s
- 4: 125 kbit/s
- 5: 100 kbit/s (not supported)
- 6: 50 kbit/s
- 7: 20 kbit/s (not supported)
- 8: 10 kbit/s (not supported)

### 3.51 Cyclic data

#### RPDOs (receive data)

- 1. Receive PDO Mapping Parameter 0:
  - Sub1: CMDdigital (object 2540sub1)
  - Sub2: SPdigital (object 2541sub1)
- 2. Receive PDO Mapping Parameter 1:
  - Sub1: PVdigital (object 2542sub1)
  - Sub2: MTEMPdigital (object 2543sub1)

#### TPDOs (transmit data)

- 1. Transmit PDO Mapping Parameter 0:
  - Sub1: POS (object 2500sub1)
  - Sub2: CMD (object 2501sub1)
- 2. Transmit PDO Mapping Parameter 1:
  - Sub1: CMDanalog (object 2502sub1)
  - Sub2: SPanalog (object 2503sub1)
- 3. Transmit PDO Mapping Parameter 2:
  - Sub1: PVanalog (object 2504sub1)
  - Sub2: SP (object 2C1Asub3)

### 3.52 Switching between position controller and process controller

The process controller has to be first activated via the ADD.FUNCTION menu. You can then switch between P.CO and X.CO via object PCONact (2C02sub17)